

Polynomial factor models: non-iterative estimation via method-of-moments

Florian Schubert^{1,2} Rebecca Büchner³ Karin Schermelleh-Engel³
Theo K. Dijkstra⁴

¹University of Würzburg, Germany

²University of Twente, The Netherlands

³University of Frankfurt, Germany

⁴University of Groningen, The Netherlands

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Example of a polynomial factor model:

$$\begin{aligned}\eta_4 = & \gamma_1\eta_1 + \gamma_2\eta_2 + \gamma_3\eta_3 + \\ & \gamma_{11}(\eta_1^2 - 1) + \gamma_{22}(\eta_2^2 - 1) + \\ & \gamma_{12}(\eta_1\eta_2 - E(\eta_1\eta_2)) + \gamma_{112}(\eta_1^2\eta_2 - E(\eta_1^2\eta_2)) \\ & \gamma_{123}(\eta_1\eta_2\eta_3 - E(\eta_1\eta_2\eta_3)) + \zeta_1.\end{aligned}\tag{1}$$

All latent variables (LVs) are standardized, and the structural error term ζ_1 is independent of the LVs on the right-hand side of the equation, i.e., ζ_1 is independent of η_1 , η_2 , and η_3 .

Measurement model

Each LV is connected to at least two indicators and each block of indicators is connected to one LV only:

$$\mathbf{y}_i = \lambda_i \eta_i + \epsilon_i. \quad (2)$$

The indicators are standardized and the measurement errors are mutually independent and independent of the η 's. The correlation matrix of the indicators of one block can be calculated as

$$E(\mathbf{y}_i \mathbf{y}_i') = \Sigma_{ii} = \lambda_i \lambda_i' + \Theta_i, \quad (3)$$

where the covariance matrix of the measurement errors Θ_i is diagonal. The correlation matrix of the indicators of different blocks ($i \neq j$):

$$E(\mathbf{y}_i \mathbf{y}_j') = \Sigma_{ij} = \rho_{ij} \lambda_i \lambda_j'. \quad (4)$$

Proxies and weights

To estimate the model parameters, we build a proxy for each latent variable as weighted linear combination of its indicators. The weights used to build the proxy for latent variable i are obtained as

$$\hat{\mathbf{w}}_i \propto \sum_{j \neq i} e_{ij} \mathbf{S}_{ij} \mathbf{w}_j \text{ (one-step weights),} \quad (5)$$

where \mathbf{w}_j is an arbitrary vector of the same length as \mathbf{y}_j and $e_{ij} = \text{sign}(\mathbf{w}_j' \mathbf{S}_{ij} \mathbf{w}_j)$. Both weight vectors \mathbf{w}_j and $\hat{\mathbf{w}}_i$ are scaled: $\mathbf{w}_j' \mathbf{S}_{jj} \mathbf{w}_j = 1$ and $\hat{\mathbf{w}}_i' \mathbf{S}_{ii} \hat{\mathbf{w}}_i = 1$.

The probability limit of $\hat{\mathbf{w}}_i$ is

$$\text{plim}(\hat{\mathbf{w}}_i) = \bar{\mathbf{w}}_i = \lambda_i / \sqrt{\lambda_i' \boldsymbol{\Sigma}_{ii} \lambda_i} = \lambda_i / c_i. \quad (6)$$

Estimation of the loadings

Calculate the correction factor \hat{c}_i such that the squared difference between the off-diagonal elements of

$$\mathbf{S}_{ii} \text{ and } \hat{c}_i \hat{\mathbf{w}}_i \hat{c}_i \hat{\mathbf{w}}_i' \quad (7)$$

is minimized. As a result, we obtain

$$\hat{c}_i = \sqrt{\frac{\hat{\mathbf{w}}_i' (\mathbf{S}_{ii} - \text{diag}(\mathbf{S}_{ii})) \hat{\mathbf{w}}_i}{\hat{\mathbf{w}}_i' (\hat{\mathbf{w}}_i \hat{\mathbf{w}}_i' - \text{diag}(\hat{\mathbf{w}}_i \hat{\mathbf{w}}_i')) \hat{\mathbf{w}}_i}}, \quad (8)$$

where $\text{diag}(\mathbf{S}_{ii})$ is the diagonal matrix of \mathbf{S}_{ii} .

Since $\text{plim}(\hat{c}_i) = \sqrt{\lambda_i' \Sigma_{ii} \lambda_i}$, the factor loadings can be consistently estimated by $\hat{c}_i \hat{\mathbf{w}}_i = \hat{\lambda}_i$.

Relationship between latent variables and proxies

We define a population proxy:

$$\bar{\eta}_i = \bar{\mathbf{w}}_i' \mathbf{y}_i = (\bar{\mathbf{w}}_i' \boldsymbol{\lambda}_i) \eta_i + \bar{\mathbf{w}}_i' \boldsymbol{\epsilon}_i = Q_i \eta_i + \delta_i, \quad (9)$$

where Q_i (quality) is the correlation between the proxy and its latent variable. The δ 's (as the ϵ 's) have zero means and are mutually independent and independent of the η 's.

Replacing $\boldsymbol{\lambda}_i$ by $c_i \bar{\mathbf{w}}_i$ in Q_i , we obtain

$$Q_i = \bar{\mathbf{w}}_i' \boldsymbol{\lambda}_i = c_i \bar{\mathbf{w}}_i' \bar{\mathbf{w}}_i. \quad (10)$$

We can estimate the quality by

$$\hat{Q}_i = \hat{c}_i \hat{\mathbf{w}}_i' \hat{\mathbf{w}}_i. \quad (11)$$

Relationship between latent variables and proxies

Relationship between the correlation of the proxies and the correlation between the latent variables:

$$E(\bar{\eta}_i \bar{\eta}_j) = Q_i Q_j E(\eta_i \eta_j), \quad (12)$$

where $E(\bar{\eta}_i \bar{\eta}_j)$ is estimated by the sample covariance between the proxies i and j .

Using PLS weights, this is already known and published:

- for linear models by [Dijkstra, T.K. & Henseler, J., 2015], and
- for polynomial models by [Dijkstra, T. K. & Schermelleh-Engel, K., 2014].

New:

- the use of one-step weights
- implementation in the MoMpoly package in R [Schuberth, F. & Dijkstra, T. K. & Schamberger, T., 2017]

Non-iterative method-of-moments

Starting point is a (regression) equation with a two-way interaction term:

$$\eta_3 = \gamma_1\eta_1 + \gamma_2\eta_2 + \gamma_{12}(\eta_1\eta_2 - E(\eta_1\eta_2)) + \zeta_1. \quad (13)$$

The γ 's can be obtained by solving the following moment equations:

$$\begin{pmatrix} E(\eta_1\eta_3) \\ E(\eta_2\eta_3) \\ E(\eta_1\eta_2\eta_3) \end{pmatrix} = \begin{pmatrix} 1 & E(\eta_1\eta_2) & E(\eta_1^2\eta_2) \\ & 1 & E(\eta_1\eta_2^2) \\ & & E(\eta_1^2\eta_2^2) - E(\eta_1\eta_2)^2 \end{pmatrix} \begin{pmatrix} \gamma_1 \\ \gamma_2 \\ \gamma_{12} \end{pmatrix}, \quad (14)$$

where the moments are given by:

$$E(\bar{\eta}_i\bar{\eta}_j) = Q_i Q_j E(\eta_i\eta_j), \quad (15)$$

$$E(\bar{\eta}_i^2\bar{\eta}_j) = Q_i^2 Q_j E(\eta_i^2\eta_j), \quad (16)$$

$$E(\bar{\eta}_i^2\bar{\eta}_j^2) = Q_i^2 Q_j^2 (E(\eta_i^2\eta_j^2) - 1) + 1, \text{ and} \quad (17)$$

$$E(\bar{\eta}_i\bar{\eta}_j\bar{\eta}_k) = Q_i Q_j Q_k E(\eta_i\eta_j\eta_k). \quad (18)$$

So far, **no distributional assumptions are necessary**. We only assume that

- the moments exist,
- the measurement errors are mutually independent and independent of the η 's, and
- that the structural error term is independent of the η 's of the right-hand side of the equation.

Non-iterative method-of-moments

Adding quadratic terms to the equation with the two-way interaction term:

$$\eta_3 = \gamma_1 \eta_1 + \gamma_2 \eta_2 + \gamma_{11}(\eta_1^2 - 1) + \gamma_{12}(\eta_1 \eta_2 - E(\eta_1 \eta_2)) + \gamma_{22}(\eta_2^2 - 1) + \zeta_1. \quad (19)$$

Higher moments are required and therefore more assumptions are necessary, in particular, assumptions about the higher-order moments of the δ 's:

$$E(\bar{\eta}_i^3) = Q_i^3 E(\eta_i^3) + E(\delta_i^3), \quad (20)$$

$$E(\bar{\eta}_i^4) = Q_i^4 E(\eta_i^4) + 6Q_i^2(1 - Q_i^2) + E(\delta_i^4), \text{ and} \quad (21)$$

$$E(\bar{\eta}_i^3 \bar{\eta}_j) = Q_i^3 Q_j E(\eta_i^3 \eta_j) + 3E(\bar{\eta}_i \bar{\eta}_j)(1 - Q_i^2). \quad (22)$$

Assumptions about the moments of the δ 's

In the following, we assume that δ_i , has the same higher-order moments as the normal distribution, i.e.,

$$E(\delta_i^3) = 0, \text{ and} \quad (23)$$

$$E(\delta_i^4) = 3 [\text{var}(\delta_i)]^2 = 3(1 - Q_i^2)^2. \quad (24)$$

Joint normality of all exogenous variables

Instead of using the *general* moments, we can assume joint normality for all exogenous variables ϵ 's, ζ , and exogenous η 's . Considering again the equation of example above:

$$\begin{pmatrix} E(\eta_1\eta_3) \\ E(\eta_2\eta_3) \\ E(\eta_1\eta_2\eta_3) \end{pmatrix} = \begin{pmatrix} 1 & E(\eta_1\eta_2) & E(\eta_1^2\eta_2) \\ & 1 & E(\eta_1\eta_2^2) \\ & & E(\eta_1^2\eta_2^2) - E(\eta_1\eta_2)^2 \end{pmatrix} \begin{pmatrix} \gamma_1 \\ \gamma_2 \\ \gamma_{12} \end{pmatrix}. \quad (25)$$

Assuming joint normality leads to:

$$\begin{pmatrix} E(\eta_1\eta_3) \\ E(\eta_2\eta_3) \\ E(\eta_1\eta_2\eta_3) \end{pmatrix} = \begin{pmatrix} 1 & \rho_{12} & 0 \\ & 1 & 0 \\ & & 1 + \rho_{12}^2 \end{pmatrix} \begin{pmatrix} \gamma_1 \\ \gamma_2 \\ \gamma_{12} \end{pmatrix}, \quad (26)$$

where $\rho_{12} = E(\bar{\eta}_1\bar{\eta}_2)/(Q_1Q_2)$. Covariances between the LVs of the RHS and the dependent LV are calculated as above. In principle every recursive model can be estimated in this way.

Setting:

- Structural model:

$$\eta_3 = 0.3\eta_1 + 0.4\eta_2 + 0.12(\eta_1^2 - 1) + 0.15(\eta_1\eta_2 - 0.3) + 0.1(\eta_2^2 - 1) + \zeta_1. \quad (27)$$

- Correlation between η_1 and η_2 is set to $\rho_{12} = 0.3$
- Each latent variable is connected with 3 indicators with $\lambda'_i = (0.9 \quad 0.85 \quad 0.8)$
- Sample size of $N = 400$ and 500 runs
- Estimators: MoMpoly with one-step weights, and Latent Moderated Structural Equations (LMS) [Klein, A. & Moosbrugger, H., 2000]

Results

Para.	true	mean MoMpoly ¹	mean LMS ²	sd MoMpoly ¹	sd LMS ²
γ_1	0.30	0.298	0.297	0.048	0.047
γ_2	0.40	0.403	0.402	0.047	0.045
γ_{11}	0.12	0.118	0.117	0.044	0.041
γ_{12}	0.15	0.147	0.147	0.062	0.059
γ_{22}	0.10	0.104	0.101	0.042	0.039
ρ_{12}	0.30	0.300	0.299	0.052	0.052
λ_{11}	0.90	0.898	0.899	0.044	0.017
λ_{12}	0.85	0.854	0.852	0.052	0.018
λ_{13}	0.80	0.795	0.800	0.058	0.022

¹Inadmissible results are removed, therefore the results are based on 484 estimations.

²No inadmissible results were produced.

Second simulation

Our approach can also deal with several recursive equations. For demonstration, we run a second simulation using the following model:

$$\eta_3 = 0.5\eta_1 - 0.4\eta_2 + \zeta_1 \quad (28)$$

$$\eta_4 = 0.35\eta_1 + 0.2\eta_3 + 0.1(\eta_3^2 - 1) + \zeta_2 \quad (29)$$

$$\eta_5 = 0.3\eta_2 - 0.25\eta_4 + 0.3(\eta_3\eta_4 - 0.333) + \zeta_3 \quad (30)$$

- $E(\eta_1\eta_2) = 0.3$
- Each latent variable is connected with 3 indicators with $\lambda'_i = (0.9 \quad 0.85 \quad 0.8)$
- Sample size of $N = 400$ and 500 runs
- Estimator: MoMpoly with one-step weights

Para.	true	mean ¹	sd ¹
γ_{31}	0.500	0.502	0.049
γ_{32}	-0.400	-0.395	0.053
γ_{41}	0.350	0.347	0.056
γ_{43}	0.200	0.201	0.058
γ_{433}	-0.100	-0.099	0.038
γ_{52}	0.300	0.301	0.050
γ_{54}	-0.250	-0.247	0.052
γ_{534}	0.300	0.298	0.052
ρ_{12}	0.300	0.299	0.051
λ_{51}	0.900	0.895	0.054
λ_{51}	0.850	0.846	0.061
λ_{51}	0.800	0.803	0.068

¹Inadmissible results are removed, therefore the results are based on 475 estimations.

The MoMpoly package

Model specification in *lavaan* syntax [Rosseel, Y., 2012], e.g.,

```
model='  
  ETA3~ETA1+ETA2+ETA1.ETA1+ETA1.ETA2+ETA2.ETA2  
  ETA1 =~ y1+y2+y3  
  ETA2 =~ y4+y5+y6  
  ETA3 =~ y7+y8+y9  
'
```

The model can be estimated by the `MoMpoly` function from the *MoMpoly* package:

```
MoMpoly(model, data)
```

Capabilities of the MoMpoly package

It is capable to deal with:

- single equations using
 - the *general* moments (however, skewness and kurtosis of the δ 's from the normal distribution are used)
 - the moments from the multivariate normal distribution (all exogenous variables: ϵ 's, ζ , and exogenous η 's are jointly normally distributed)
- correlated measurement error within a block
- several recursive equations using the moments from the multivariate normal distribution (all exogenous variables: ϵ 's, and ζ 's, and exogenous η 's are jointly normally distributed) where the parameter estimates
 - are retrieved from reduced form coefficient matrix
 - are obtained from replacing equation by equation
- several recursive equations using the *general* moments. The parameters are estimated equation by equation (limited to LVs up to higher-order 3)
- single-indicator latent variables

Further options in the MoMpoly function and functions

```
MoMpoly(model, data, criterionload=criterion.geometric,  
         criterionpath=criterion.diff, normality=F,  
         weightFun=weightFun.onestep,  
         KindOfEstimation=approach.none, ...)
```

Further options in the MoMpoly function:






- different ways to obtain the correction factor \hat{c}_i
- different correction factor for loadings and path coefficients
- different weights: one-step weights, PLS weights, or prescribed weights

Further functions:

- `MoMpoly.boot()`: combination of the MoMpoly function with the *boot* package
- `MoMpoly.jack()`: function to obtain Jackknife standard errors

- Elaboration of the measurement model via instrumental variable techniques
- Other higher-order moments for delta than those from the normal distribution)
- Robustness against model misspecifications

Thank you!
Questions/Comments?

-  Dijkstra, T. K. & Schermelleh-Engel, K., (2014)
Consistent partial least squares for nonlinear structural equation models
Psychometrika 79(4) 585 – 604.
-  Dijkstra, T.K. & Henseler, J. (2015)
Consistent and asymptotically normal PLS estimators for linear structural equations
Computational Statistics & Data Analysis, 81, 10 – 23.
-  Klein, A. & Moosbrugger, H. (2000)
Maximum likelihood estimation of latent interaction effects with the LMS method
Psychometrika, 65(4), 457 – 474.
-  Rosseel, Y. (2012)
lavaan: An R Package for Structural Equation Modeling
Journal of Statistical Software, 48(2), 1 – 36.
-  Schubert, F., Schamberger, T. & Dijkstra, T. K. (2017)
MoMpoly package (version 0.1.3.) *available upon request*.

Results first simulation

Para.	true	mean	sd
γ_1	0.300	0.298	0.048
γ_{11}	0.120	0.118	0.044
γ_{12}	0.150	0.147	0.062
γ_2	0.400	0.403	0.047
γ_{22}	0.100	0.104	0.042
ρ_{12}	0.300	0.300	0.052
λ_{31}	0.900	0.896	0.034
λ_{32}	0.850	0.850	0.039
λ_{33}	0.800	0.797	0.041
λ_{11}	0.900	0.898	0.044
λ_{12}	0.850	0.854	0.052
λ_{13}	0.800	0.795	0.058
λ_{21}	0.900	0.898	0.037
λ_{22}	0.850	0.850	0.044
λ_{23}	0.800	0.800	0.049

Results second simulation

Para.	true	mean	sd	Para	true	mean	sd
γ_{31}	0.500	0.502	0.049	λ_{41}	0.900	0.898	0.040
γ_{32}	-0.400	-0.395	0.053	λ_{42}	0.850	0.850	0.043
γ_{41}	0.350	0.347	0.056	λ_{43}	0.800	0.800	0.048
γ_{43}	0.200	0.201	0.058	λ_{51}	0.900	0.895	0.054
γ_{433}	-0.100	-0.099	0.038	λ_{52}	0.850	0.846	0.061
γ_{52}	0.300	0.301	0.050	λ_{53}	0.800	0.803	0.068
γ_{534}	0.300	0.298	0.052	λ_{11}	0.900	0.897	0.035
γ_{54}	-0.250	-0.247	0.052	λ_{12}	0.850	0.851	0.040
ρ_{12}	0.300	0.299	0.051	λ_{13}	0.800	0.799	0.042
λ_{31}	0.900	0.904	0.036	λ_{21}	0.900	0.897	0.041
λ_{32}	0.850	0.847	0.040	λ_{22}	0.850	0.848	0.046
λ_{33}	0.800	0.797	0.045	λ_{23}	0.800	0.803	0.049